X8+
Operation Manual

Important: Read before flying!
Meet the X8+

Thank you for purchasing an X8+!

The X8 is a powerful octocopter platform for aerial video. Review this manual in its entirety before your first flight. Additional instructions can be found in the X8 information portal at 3DR.com/X8/info.

Happy flying!
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Parts

RC Controller | Propellers | Battery Kit | Ground Station Radio | Tool Kit | Flight Checklist
---|---|---|---|---|---
| | SF propellers (4) | Flight battery | Radio | Propeller wrench |
| | SFP propellers (4) | Charger and accessories | USB adapter | |
| | | Guard bag | Android adapter | Pixhawk micro-SD card adapter |

- **RC Controller**
- **Propellers**
  - SF propellers (4)
  - SFP propellers (4)
- **Battery Kit**
  - Flight battery
  - Charger and accessories
  - Guard bag
- **Ground Station Radio**
  - Radio
  - USB adapter
  - Android adapter
- **Tool Kit**
  - Propeller wrench
- **Flight Checklist**
Setup: Assembly

The X8 arrives in travel configuration. Complete these steps to prepare the X8 for flight.

1 Unfold Arms

Remove the bolts and thumbnuts outside the two folded black arms (1). Unfold the black arms, re-insert the bolts, and secure with the thumbnuts (2).
2 Unfold Legs

Remove the bolts and nuts to the inside of the folded legs (1), unfold the legs, re-insert the bolts, and secure with the nuts (2).

3 Attach Propellers

The X8 uses SF and SFP propellers. These labels can be found on the individual propeller packages and on the propellers themselves. See the diagram below for which motors require SF or SFP propellers. The accuracy of this assembly is critical for the X8 to fly correctly.

To attach each propeller, remove the nut and washer from the motor, and add the correct type of propeller with the writing on the propeller facing the sky. (This will be a tight fit; apply pressure and twist the propeller onto the motor.) Replace the washer over the propeller, and tighten the nut on top using the propeller wrench.

Ensure that the writing on all propellers faces the sky.
Ground Station

A ground station is a laptop or tablet running an ArduPilot-compatible mission control application. In the field, a ground station helps you monitor the X8 during flight, plan missions, and troubleshoot issues. We recommend using a ground station at all times with the X8.

To set up a ground station, choose a platform below and visit 3DR.com/download_software to install the application.

- **DroidPlanner 2** (Android)
- **Mission Planner** (Windows)
- **APM Planner** (OS X)

**Important Note About Vehicle Setup in Mission Planner and APM Planner:**
Your X8 has been pre-configured at the factory and is ready to fly. Re-performing the calibrations on the *Initial Setup* screen, including the mandatory hardware configurations and setup wizard, can adversely affect the performance of your aircraft.

**iOS?** There are currently no ground station applications available for iOS.
Power Management

The X8 is powered by a rechargeable lithium polymer (LiPo) battery. When fully charged, the battery provides up to 15 minutes of flight time depending on payload, environmental conditions, and flying style. Flying with a gimbal, GoPro, and FPV system can reduce flight time by up to 5 minutes. Flying aggressively or in high winds can affect power consumption and reduce flight time. Monitor power consumption using the flight data display on the controller (press and hold the DN button).

When the battery reaches the low voltage limit, the X8 will initiate a low battery failsafe and land automatically at the current position. (See page 20 for more information about failsafes.) To avoid a low battery failsafe, monitor battery voltage during flight on the controller’s flight data display, and end your flight before the battery reaches the low voltage limit.

Controller Flight Data Display: Screen 1

flight battery level

Full battery: 16.8 V  
Low battery limit: 14 V

⚠️ End your flight at 14.1 V.

flight battery mAh consumed since armed

Another way to monitor power consumption is by using milliamp-hours (mAh). Monitor the mAh on the controller, and ensure that it does not exceed 8,000 mAh (80% of the battery’s available capacity). Exceeding 8,000 mAh can render the battery permanently unusable.

⚠️ Do not exceed 8,000 mAh for a fully charged X8+ battery.
Charging

Charge the battery before your first flight!

1. Connect the charger to the power adapter cable and a wall outlet. Connect the red cable to the + port and the black cable to the - port.

2. Set the charger to LiPo and 3A.

3. Connect the white connector to the 4S port, and join the two yellow connectors together.

4. Secure the battery inside the guard bag, and charge until the status indicator displays green.

Safety

Flying with a low battery is a safety risk and can render the battery permanently unusable. Always fly with a fully charged battery.

Charge the battery using a designated LiPo balance charger only. Always monitor the battery while charging. Protect the battery from extreme heat, extreme cold, puncturing, and flammable surfaces. Always transport, charge, and store the battery in the guard bag.

Inspect the battery for damage before and after flying. If you observe any swelling of the package or the battery ceases to function, do not use the battery; locate your local battery recycling center, and dispose of the battery. In the US and Canada, visit call2recycle.org to find a location. Do not dispose of the battery in the trash.
Controller Battery

The controller is powered by 8 AA batteries (included). The controller’s flight data display allows you to monitor the voltage of the controller. When fully charged, the controller will display 12 V; when completely out of charge, the controller will display 9 V. Replace the batteries when the controller displays 9.1 V.

Press and hold the **DN** button to view flight data.

Controller Flight Data Display: Screen 1

- **RX:** 99%
- **Lock:**
- **Loiter:**
- **Alt:** 24
- **Sats:** 10
- **Spd:** 13
- **Batt:** 14.8
- **Dist:** 42
- **mAh:** 1834
- **Time:** 01:45
- **Tx Batt:** 10.4

**controller battery level (9-12 V)**

⚠️ Replace controller batteries at 9.1 V.
Powering the X8

Follow these steps to power the X8.

1. Turn on the controller. Ensure that the switches are set to CH 7 OFF, STD, and RTL OFF.

2. Join the yellow connector on the battery with the yellow connector on the X8; this will power on the X8. Keep the X8 still and level while it powers on and initializes the sensors. Check the status LED; when it displays blinking blue, the sensors have completed initialization and you can move the X8.

3. When the initialization process is complete, turn over the X8 and secure the battery to the underside of the vehicle using the velcro straps.

Status LED indicators:

- Initializing, keep still and level
- Initializing complete

It is important to establish communication before powering on the X8. Always turn on the controller before connecting the battery. When powering off the X8, disconnect the battery before turning off the controller.
Connecting to a Ground Station

To connect the X8 to a ground station, connect the ground station radio to your laptop or tablet, and power the X8.

Laptop (Mission Planner/APM Planner)

1. Connect the ground station radio to your laptop using the USB adapter. Open Mission Planner or APM Planner.

2. Select 57600 and AUTO, then select CONNECT. (When connecting directly to Pixhawk’s micro-USB port, set the rate to 115200.)

3. Select Flight Data to view live data from the X8.

Tablet (DroidPlanner)

1. Connect the blue end of the Android adapter to your device and the black end to the radio.

2. Select Connect.
Flight Basics: Safety

To ensure safe and successful flying, always fly in accordance with your location regulations and these best operating practices.

Before you fly, determine the boundaries of your safe flying area. If the X8 moves outside the designated area or exhibits instability in flight, switch to standard mode and land the X8 manually.

The X8 will not avoid obstacles on its own, including during missions. As the operator, it’s your job to recognize and avoid obstructions while flying. Always be ready to regain manual control of the X8 in the event of an unsafe situation.

Location

Always fly below 400 ft (120 m) and within your visual line of sight. Don’t let the X8 get too far away from you; make sure you can always see its orientation. Don’t fly in low light, heavy wind, rain, or other conditions that might impede visibility.

Propellers

Spinning propellers can cause serious injury. The safety button indicates the status of the motors to help you prevent hazardous contact with the X8’s high-speed propellers.

- When the X8 is powered on, the safety button will blink red, indicating that the motors are inactive and the propellers are safe to handle.
- When you’re ready to fly, press and hold the safety button until it shows solid red. This indicates that the motors are active and the propellers can spin if armed. To make the propellers safe to handle again, press and hold the safety button until it blinks red.

Always fly at least 100 feet (30 m) away from people, vehicles, and buildings. Make the safety of people and property your first priority!

Always fly at least 5 miles (8 km) away from airports and other areas where pilots operate manned aircraft.
Operating Limits

Always fly within the X8’s operating limits.

### X8+ Operating Limits

<table>
<thead>
<tr>
<th>Limit</th>
<th>Specification</th>
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</thead>
<tbody>
<tr>
<td>Maximum Altitude*</td>
<td>100 m (328 ft)</td>
</tr>
<tr>
<td>Range*</td>
<td>300 m (984 ft) from launch point</td>
</tr>
<tr>
<td>GPS Lock</td>
<td>GPS lock required at all times</td>
</tr>
<tr>
<td>Maximum estimated flight time</td>
<td>15 min</td>
</tr>
<tr>
<td>Payload capacity</td>
<td>800 g (1.7 lbs)</td>
</tr>
</tbody>
</table>

*While geofence enabled (default)
Controls

Maneuver the X8 in flight using the controller’s two joysticks.

**Throttle**

Move the left stick vertically to control altitude.

---

To take off and to gain altitude, raise the throttle stick slightly above center position.

Set the throttle stick to center to maintain the current altitude.

Lower the throttle stick below center to decrease altitude.

Set the throttle stick fully down to land once the X8 is a few inches above the ground.
Yaw

Move the left stick horizontally to rotate the X8 and change orientation. For a slow rotation, move the stick slightly away from the center in either direction. Moving the stick farther from the center creates a faster rotation.

Flight Tip
When adjusting orientation, move the left stick horizontally without changing its vertical position.
Pitch and Roll

The right stick allows you to control the X8’s position in the air. Move the right stick to tell the X8 to move in that direction: forward (toward the blue arms), back (toward the black arms), left (toward the left arms), or right (towards the right arms). How far you move the stick from the center before releasing it tells the X8 how fast to move.

**Flight Tip**
The X8 moves according to its orientation. The blue arms face forward, and the black arms face backward. Before using the right stick, use yaw to keep the X8 facing in outward orientation so that the black arms face towards you and the blue arms and face away from you.
Modes

The X8 includes three flight modes: manual flight (STD-altitude hold), hover mode (LTR-loiter), and mission flight (AUTO). Use the switch on the right side of the controller to select a flight mode.

Standard (altitude hold mode)
STD

fly manually

Start your flight in standard to select altitude hold mode, and fly manually using the controller.

Loiter mode
LTR

hover

Select loiter to hover in place automatically. Use the controller to adjust the X8’s position then release the sticks to hold that position. Loiter is a great way for beginners to learn how to fly! If you’re new to flying, start your first flight in loiter instead of standard.

⚠️ To avoid sudden changes in altitude, set the throttle stick to center position before switching modes, including in the event of a GPS failsafe. See page 20 for more information about failsafes.
Auto mode
AUTO

fly a mission

Select auto mode to fly an autonomous mission. The X8 will automatically fly the series of waypoints saved to the autopilot. See the Missions section on page 28 for instructions on planning and flying missions.

Do not activate auto mode unless you have saved a mission to the X8 using a ground station application.

Gimbal control
TILT

tilt the camera up and down

Connect a Tarot Gimbal (sold separately), and use the TILT knob to control the angle of the camera in flight. Visit 3DR.com/X8/info for instructions.

Land
CH 7

land at the current position

Set the CH 7 switch to ON to end your flight and land at the current position. Once you activate land, set the throttle stick fully down, and the X8 will automatically disarm after landing. The X8 will not disarm automatically unless the throttle stick is set fully down.

Reposition during landing: During landing, use the right stick on the controller to adjust the X8’s position.
Return to Launch

*land at the launch point*

Set the RTL switch to ON to end your flight and return the X8 to the launch point automatically. Once you activate RTL, set the throttle stick fully down, and the X8 will automatically disarm after landing. The X8 will not disarm automatically unless the throttle stick is set fully down. Ensure that the RTL switch is set to OFF before takeoff.

When commanded to RTL, the X8 will:

1. Achieve minimum altitude of 15 m (50 ft) or maintain current altitude if above 15 m.
2. Move to launch point and loiter for 5 seconds.
3. Land at launch point. Wait a few seconds and disarm automatically.

Reposition during landing: During landing, use the right stick on the controller to adjust the X8’s position.

RTL returns the X8 to the location where it was armed. Always arm the X8 at a safe, unobstructed launch point.
Failsafes

The X8 is programmed with a set of failsafe behaviors to prevent a crash in the event of a loss of one of the data or communication channels required for flight. Although certain failsafes have assigned LED indicators and tones, it is unlikely that you will be able to see these at a distance. Monitor the ground station for failsafe indications. If a failsafe is triggered, the assigned behavior will activate. To override the failsafe behavior, use the controller to switch to standard mode and regain manual control.

**RC Controller Signal Failsafe**
Physical obstructions and interference from nearby wireless signals can affect the X8’s connection with the controller.

If the X8 loses contact with the controller, it will return to the launch point automatically and land, indicated by a blinking yellow status LED.

**Low Battery Failsafe**
Environmental conditions, payload, and flying style can affect power consumption. Use the controller’s flight data display to monitor the voltage of the battery during flight.

If the battery reaches 14 V, the X8 will land automatically at the current position, indicated by a blinking yellow status LED and a quick repeating tone.
GPS Failsafe
The X8 requires GPS lock before takeoff. Enclosed areas, physical obstructions, and lack of available satellites can affect GPS strength. If the X8 loses GPS lock in flight, it will trigger a GPS failsafe, indicated by a blinking blue and yellow LED with a high-high-high-low tone, and automatically switch to manual control (standard - altitude hold mode). Always be prepared to regain manual control at any time while flying and choose an unobstructed flying area to improve GPS signal strength. When flying a mission, we recommended changing the GPS failsafe behavior to land. (Visit 3DR.com/X8/info for more information about configuring the GPS failsafe.)

Altitude Failsafe
The X8 has a 100 m (328 ft) altitude geofence enabled by default. If the geofence is breached, the X8 will automatically RTL.

Range Failsafe
The X8 has a 300 m (984 ft) horizontal geofence enabled by default. If the X8 travels farther than 300 m from the launch point, it will automatically return to the launch point and land. If you plan to fly a mission that exceeds this range, you will need to disable the horizontal geofence. (Visit 3DR.com/X8/info for instructions.) The range failsafe will be disabled in the event of a GPS failsafe.
Status Indicators

LED

The Pixhawk LED indicates the status of the X8. During flight, the LED won’t be visible, so you will need to use a ground station to view the status of the X8. Visit 3DR.com/X8/info to listen to Pixhawk’s status tones.

- Initializing, hold the X8 still and level
- Acquiring GPS, please wait
- Autopilot ready, GPS locked
- Armed
- Loss of RC signal, automatic landing
- Low battery, automatic landing
- Loss of GPS signal, switch to standard mode (altitude hold)
- Pre-arm safety check failure. Connect to a ground station and see the troubleshooting section.
Safety Button

The safety button indicates the status of the motors to allow you to arm and disarm the X8 safely.

Motors inactive, safe to handle
Motors active, deactivate before handling
Flight Procedures: Takeoff

Follow these steps to take off.

Checklist

» Propellers are attached tightly to the motors in the correct order and the GPS mast is oriented vertically.

» The X8 is powered with the battery secured to the underside of the vehicle. (Remember to hold the X8 still and level while the sensors initialize.)

» The controller is set to CH 7 OFF, standard (STD) mode (loiter mode for beginners), and RTL OFF.

» The status LED displays blinking green, indicating that the X8 has acquired GPS lock. This can take a few minutes depending on your flying location.

» The X8 is situated at a safe, unobstructed launch point, facing away from you.
Arm

After completing the checklist, you’re ready to fly! Arming and disarming are important steps that must be completed before takeoff and after landing. There are two steps to arming the X8: the safety button and the controller.

1
Press and hold the safety button until it displays solid red. This indicates that the X8 is now active. **Stand back!**

- Motors inactive, safe to handle
- Motors active, deactivate before handling

Safety button indicators

2
To arm the motors, hold the left stick down/right until the motors spin.

Controller left stick: arming position

The arming and disarming procedures ensure that you can safety start and stop motors without risk of injury. The X8’s motors will spin when armed! Make sure the propellers are clear of any obstructions, including your hands, before arming. Do not handle the propellers or pick up the X8 while the safety button is active (solid red).
Landing

If you end your flight using the Ch 7 land command or RTL, the X8 will disarm automatically; wait for the motors to stop, and proceed to powering off. Attempting to disarm the X8 in either land or RTL can cause the copter to flip.

Disarm

For manual landing in standard or loiter mode:

1. Press and hold the safety button until it blinks red. The motors are now inactive, and the X8 is safe to handle.

2. To disarm the motors, hold the left stick down/left until the motors stop.

- ● ● ● ○ Motors inactive, safe to handle
- ● ● ● ● Motors active, deactivate before handling

Safety button indicators

Controller left stick: disarming position

Do not handle the propellers or pick up the copter while the safety button is active (solid red). Remember to disconnect the battery before turning off the controller when powering off.
Monitoring

Monitor the X8 in flight using the controller’s flight data screens.

Press and hold the DN button to access the flight data screens. Press DN again to toggle between screens.

- Current flight mode
- GPS signal strength in # of satellites
- Flight battery level (14-16.8 V)
- Flight battery mAh consumed since armed
- End your flight at 14.1 V. Do not exceed 8000 mAh for a fully charged X8+ battery (80% of available capacity).
- Controller battery level (9-12 V)
Missions

The X8’s Pixhawk autopilot is capable of flying an autonomous mission without operator input. Ensure that you feel comfortable operating the X8 manually before attempting an autonomous mission.

Environmental Awareness

Before you fly, assess the features of your flying area. Determine the boundaries of the safe flying area, and be prepared to recover the copter manually if it goes outside this area. Be aware of any risks at your location, including bodies of water, structures, trees, etc. Designate a few areas as safety zones where you can safely land the copter in case of an unsafe situation.

Radio Signal Conditions

Flying behind solid objects, like buildings and trees, will block radio signals. Always maintain visual contact with the copter to ensure that the radio signal is unobstructed. Radio towers, cell phone towers, and nearby WiFi signals can also cause interference with the radio system and decrease its range. Avoid flying in populated areas to avoid sources of interference.

Altitude

Select an appropriate altitude for your flying location and local regulations. Remember the X8 will not avoid obstacles during a mission; it will complete the mission as planned. Select altitudes that avoid any obstacles, such as trees, and comply with the safety information in this manual.

Speed

By default, the X8 will travel at 6.5 m/s (14.5 mph) during a mission.

Power

As the operator, it is your responsibility to ensure that all missions comply with the X8’s operating limits, including flight time. Don’t forget to take into account the effect of current wind conditions on power consumption.

Regaining Manual Control

During a mission, keep the controller easily accessible, and be prepared to regain manual control at any time. To regain manual control during the mission, switch to standard mode using the controller. If you observe instability in the X8’s flight behavior or it the copter moves outside your designated safe flying area, switch to RTL. Turning off the controller will automatically trigger an RTL and can be used in an emergency situation as a hard recall command.

Failsafes

The X8’s default failsafe behaviors are optimized for manual flight. For autonomous missions, we recommend re-configuring the failsafe settings for your flying location. For instructions, visit 3DR.com/X8/info.
Planning

To plan a mission, power the X8 and connect to your ground station. Ground station applications require an Internet connection to access maps.

**Tablet (DroidPlanner)**

Select the DroidPlanner icon, select Editor. Tap to add waypoints, or select the brush tool and draw a path for the X8 to follow.

**Laptop (Mission Planner, APM Planner)**

Select Flight Plan, and click to add waypoints. Select the green arrows at the bottom of the screen to configure altitude and change waypoint types.

**Takeoff and Landing**

Both ground station options provide the choice to configure automatic takeoff and landing into the mission. Missions without automatic takeoff and landing must be initiated and ended in flight.
Saving

After planning the mission, save the mission to the X8. The Pixhawk autopilot can store one mission at a time. When you initiate the mission, the X8 will start the mission stored to the autopilot at the time.

**Tablet (DroidPlanner)**

Select the option menu in the top-right corner, and select *Send Mission*. This will save the mission to the X8.

![DroidPlanner: Send Mission (option menu)]

**Laptop (Mission Planner, APM Planner)**

On the *Flight Plan* screen, select *Write WPs* to save the mission to the X8. Select *Save WP File* to save the mission to your computer for future use.

![Write WPs]

Mission Planner: Flight Plan
Initiating

Once you’ve saved the mission to the X8, follow these steps to fly the mission.

1 Perform a pre-mission test flight. Follow the standard takeoff procedure, and fly a brief test flight to verify that all controls (throttle, yaw, roll, and pitch) are responding normally.

2 Arm in standard mode. When you’re ready to start the mission, arm the X8 in standard (STD) mode.

3 Switch to auto mode. For automatic takeoff, arm the X8 in standard mode. Then switch to auto mode, and raise the throttle to initiate the mission. For manual takeoff, initiate the mission in flight by switching to auto mode.

Ending

End the mission according to the type of landing configured in the mission.

Automatic Landing
For missions configured with a land waypoint, the X8 will disarm automatically after landing. Ensure that the throttle stick is set fully down during landing; the X8 will not disarm automatically unless the throttle stick is set fully down.

Manual Landing
For missions without a land waypoint, switch to standard or loiter mode in flight then land manually.

To avoid sudden changes in altitude when switching from auto mode to standard mode, ensure that the left stick is set to the center position.
Appendix: Troubleshooting

Pre-Arm Safety Check Failure

If the status LED displays blinking yellow, the X8 is failing one the pre-arm safety checks. To determine the specific failure, check the heads-up display on the ground station. There will be an error message specifying the failed check.

<table>
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<tr>
<th>Failure Type</th>
<th>Action</th>
</tr>
</thead>
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<td>Radio Calibration Failure</td>
<td>Perform Radio Calibration</td>
</tr>
<tr>
<td>Accelerometer Calibration</td>
<td>Perform Accelerometer Calibration</td>
</tr>
<tr>
<td>Compass Calibration Failure</td>
<td>Perform Compass Calibration</td>
</tr>
<tr>
<td>GPS Failure</td>
<td>Wait for improved GPS signal or move to a more open area</td>
</tr>
</tbody>
</table>

Video tutorials for performing calibrations can be found at 3DR.com/X8/info.

Maintenance

Replacement parts for the X8 can be purchased at store.3DR.com.

Instructions for replacing the wiring, plates, motors, and legs of the X8 can be found at 3DR.com/X8/info.
## Specs

<table>
<thead>
<tr>
<th>Spec</th>
<th>Details</th>
</tr>
</thead>
<tbody>
<tr>
<td>Battery</td>
<td>4S 14.8V 10,000 mAh 10C</td>
</tr>
<tr>
<td>Battery Dimensions</td>
<td>6.6 in x 2.6 in x 1.4 in (16.7 cm x 6.5 cm x 3.5 cm)</td>
</tr>
<tr>
<td>Battery Weight</td>
<td>803 g</td>
</tr>
<tr>
<td>Autopilot hardware</td>
<td>Pixhawk v2.4.5</td>
</tr>
<tr>
<td>Autopilot firmware</td>
<td>ArduCopter 3.2</td>
</tr>
<tr>
<td>GPS</td>
<td>3DR u-blox GPS with Compass (LEA-6H module, 5 Hz update)</td>
</tr>
<tr>
<td>Ground Station Radio</td>
<td>3DR Radio v2 (915 MHz or 433 MHz)</td>
</tr>
<tr>
<td>Motors</td>
<td>SunnySky V2216-12 KV800 II</td>
</tr>
<tr>
<td>Frame Type</td>
<td>X</td>
</tr>
<tr>
<td>Propellers</td>
<td>APC Propeller 11x4.7 SF (4)</td>
</tr>
<tr>
<td></td>
<td>APC Propeller 11x4.7 SFP (4)</td>
</tr>
<tr>
<td>Vehicle Dimensions</td>
<td>13.7 in x 20.1 in x 11.8 in (35 cm x 51 cm x 20 cm)</td>
</tr>
<tr>
<td>Payload Capacity</td>
<td>800 g (1.7 lbs)</td>
</tr>
<tr>
<td>Vehicle Weight with Battery</td>
<td>2.56 kg (5.6 lbs)</td>
</tr>
<tr>
<td>Maximum Altitude*</td>
<td>100 m</td>
</tr>
<tr>
<td>Range*</td>
<td>300 m from launch point (1 km when geofence disabled)</td>
</tr>
<tr>
<td>Maximum Estimated Flight Time</td>
<td>15 min</td>
</tr>
</tbody>
</table>

*While geofence enabled (default)*
Resources

Thank you for being a responsible drone operator. For more information about the X8, visit the pages below.

Online information portal: 3DR.com/X8/info
3DR Support: help@3DR.com
Terms and Conditions: 3DR.com/terms

Happy flying!